Dimensionality Reduction

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Motivation

Matrices are everywhere:

- Graphs: Web or Social Network.
- Pairwise interaction between two types of entities: movie rating, image-tags
- Spatial representation: images.

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- "Narrower" means the output matrices have much less number of columns/rows.
- "Can be summarized " means we can almost recover the original matrix from the summarized matrices.

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- "Narrower" means the output matrices have much less number of columns/rows.
- "Can be summarized " means we can almost recover the original matrix from the summarized matrices.

Dimensionality reduction: find the "narrower" matrices of the original matrix.

Eigenvectors and Eigenvalues of Symmetric Matrices

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$$M\mathbf{e} = \lambda \mathbf{e}$$
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Fact 1 If **e** is an eigenvector of *M*, for any constant $c \neq 0$, $c\mathbf{e}$ is also an eigenvector of *M* (with the same eigenvalue) \Rightarrow We often require that $||\mathbf{e}||_2 = 1$.

Fact 2 If $M \in \mathbb{R}^{n \times n}$ is real and symmetric, then M has n real eigenvectors and eigenvalues \Rightarrow In this lecture, M is real, symmetric. **Fact 3** We can order

$$\lambda_1 \ge \lambda_2 \ge \ldots \ge \lambda_n$$

$$\mathbf{e}_1 \quad \mathbf{e}_2 \quad \ldots \quad \mathbf{e}_n$$
(2)

We can make $\mathbf{e}_j, \mathbf{e}_j$ orthogonal, i.e, $\mathbf{e}_i^T \mathbf{e}_j = 0$ for all $i \neq j$.

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We can make \mathbf{e}_j , \mathbf{e}_j orthogonal, i.e, $\mathbf{e}_i^T \mathbf{e}_j = 0$ for all $i \neq j$. λ_1 and \mathbf{e}_1 called the principal eigenvalue the principal eigenvector, respectively

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Eigenvectors and Eigenvalues of Symmetric Matrices - An Example

$$M = \begin{bmatrix} 3 & 2 \\ 2 & 6 \end{bmatrix}$$
(3)

has:

$$\lambda_1 = 7 \quad \text{and} \quad \mathbf{x}_1 = \begin{bmatrix} \frac{1}{\sqrt{5}}, \frac{2}{\sqrt{5}} \end{bmatrix}^T$$
$$\lambda_2 = 2 \quad \text{and} \quad \mathbf{x}_2 = \begin{bmatrix} \frac{2}{\sqrt{5}}, -\frac{1}{\sqrt{5}} \end{bmatrix}^T$$

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Finding Eigenvalues by Solving Equations

Eigenvalues are the roots of the following equation (with variable λ):

$$\det(M - \lambda \mathbf{I}) = 0 \tag{5}$$

where I is an identity matrix, and det(X) is the determinant of an $n \times n$ matrix X.

Fact 4 det $(M - \lambda \mathbf{I})$ is a degree-*n* polynomial with variable λ .

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Fact 4 det $(M - \lambda \mathbf{I})$ is a degree-*n* polynomial with variable λ . **Fact 5** If *M* is real and symmetric, Equation 5 has *n* real roots. **Fact 6** Computing the determinant of a matrix takes $O(n^3)$.

Finding Eigenvalues by Solving Equations - An example

$$M = \begin{bmatrix} 3 & 2\\ 2 & 6 \end{bmatrix} \tag{6}$$

We have:

$$\det(M - \lambda I) = \det\left(\begin{bmatrix} 3 - \lambda & 2\\ 2 & 6 - \lambda \end{bmatrix}\right) = \lambda^2 - 9\lambda + 14$$
(7)

Two roots are $\lambda_1 = 7$ and $\lambda_2 = 2$.

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Finding Eigenvalues and Eigenvectors by Power Iteration

Finding principal eigenvector and value.

POWERITERATION1(*M*) $\mathbf{v}_0 \leftarrow \text{a random vector}$ for $t \leftarrow 1$ to k $\mathbf{v}_t = \frac{M\mathbf{v}_{t-1}}{\|M\mathbf{v}_{t-1}\|}$ return $\mathbf{v}_k, \mathbf{v}_k^T M \mathbf{v}_k$.

Running time O((m+n)k) where m is the number of non-zeros of M.
e₁ ≈ v_k and λ₁ ≈ v_k^TMv_k.

Power Iteration - An example

$$M = \begin{bmatrix} 3 & 2 \\ 2 & 6 \end{bmatrix}$$
(8)

and $\mathbf{v}_0 = [1, 1]^T$. Then

$$M\mathbf{v}_0 = \begin{bmatrix} 3 & 2\\ 2 & 6 \end{bmatrix} \begin{bmatrix} 1\\ 1 \end{bmatrix} = \begin{bmatrix} 5\\ 8 \end{bmatrix}$$
(9)

Thus, $\mathbf{v}_1 = \frac{M \mathbf{v}_0}{||M \mathbf{v}_0||_2} = [0.530, 0.848]^T$. Repeat second time we get:

$$\mathbf{v}_2 = [0.471, 0.882]^T \tag{10}$$

The limiting vector is:

$$\mathbf{v}_k = [0.447, 0.894]^{\mathsf{T}} \tag{11}$$

with $\lambda = \mathbf{v}_k^T M \mathbf{v}_k = 6.993$

Finding Eigenvalues and Eigenvectors by Power Iteration

Finding the second largest eigenvalues and vectors

PowerIteration2(*M*) $(\mathbf{e}_1, \lambda_1) \leftarrow \text{PowerIteration1}(M)$ $\mathbf{v}_0 \leftarrow \text{a random vector}$ $M_2 \leftarrow M - \lambda_1 \mathbf{e}_1 \mathbf{e}_1^T$ for $t \leftarrow 1$ to k $\mathbf{v}_t = \frac{M_2 \mathbf{v}_{t-1}}{||M \mathbf{v}_{t-1}||}$ return $\mathbf{v}_k, \mathbf{v}_k^T M_2 \mathbf{v}_k$.

Running time O((m+n)k) where m is the number of non-zeros of M.
e₂ ≈ v_k and λ₂ ≈ v^T_kMv_k.

The Matrix of Eigenvectors



Then:

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The Matrix of Eigenvectors - An Example

$$M = \begin{bmatrix} 3 & 2 \\ 2 & 6 \end{bmatrix}$$
(14)

has:

$$\mathbf{x}_1 = [\frac{1}{\sqrt{5}}, \frac{2}{\sqrt{5}}]^T \qquad \mathbf{x}_2 = [\frac{2}{\sqrt{5}}, -\frac{1}{\sqrt{5}}]^T$$
 (15)

Thus,

$$E = \begin{bmatrix} \frac{1}{\sqrt{5}} & \frac{2}{\sqrt{5}} \\ \frac{2}{\sqrt{5}} & -\frac{1}{\sqrt{5}} \end{bmatrix}$$
(16)

It is straightforward to verify that:

$$EE^{T} = E^{T}E = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$
(17)

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Given a set of points $\mathcal{D} = \{x_1, x_2, \dots, x_n\}$ in \mathbb{R}^d , find a direction where all the points line up best.

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Given a set of points $\mathcal{D} = \{x_1, x_2, \dots, x_n\}$ in \mathbb{R}^d , find a direction where all the points line up best.

- A direction is a (unit) vector **w**.
- All the points line up best along w when:

$$\sum_{i=1}^{n} (\mathbf{x}_{i}^{T} \mathbf{w})^{2}$$
(18)

is maximum.



Then

$$\sum_{i=1}^{n} (\mathbf{x}_i^T \mathbf{w})^2 = ||X\mathbf{w}||_2^2 = \mathbf{w}^T X^T X \mathbf{w}$$
(20)

Thus, $\sum_{i=1}^{n} (\mathbf{x}_{i}^{T} \mathbf{w})^{2}$ is maximum when **w** is the principal eigenvector of $X^{T}X$.

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Thus, $\sum_{i=1}^{n} (\mathbf{x}_{i}^{T} \mathbf{w})^{2}$ is maximum when **w** is the principal eigenvector of $X^{T}X$. **Question:** what is $\mathbf{w}^{T}X^{T}X\mathbf{w}$ when **w** is the principal eigenvector of $X^{T}X$?



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Thus, $\sum_{i=1}^{n} (\mathbf{x}_{i}^{T} \mathbf{w})^{2}$ is maximum when **w** is the principal eigenvector of $X^{T}X$. **Question:** what is $\mathbf{w}^{T}X^{T}X\mathbf{w}$ when **w** is the principal eigenvector of $X^{T}X$? **Answer:** $\lambda_{1}(X^{T}X)$.

PCA - An Example

$$X = \begin{bmatrix} 1 & 2 \\ 2 & 1 \\ 3 & 4 \\ 4 & 3 \end{bmatrix} \text{ and } X^{T}X = \begin{bmatrix} 30 & 28 \\ 28 & 30 \end{bmatrix}$$

has $\lambda_1(X^T X) = 58$ with vector $\mathbf{x}_1 = [\frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}}]^T$

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Given a set of points $\mathcal{D} = \{x_1, x_2, \dots, x_n\}$ in \mathbb{R}^d , find the second best direction where all the points line up best.

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- $\mathbf{u}^T \mathbf{w} = 0$, here \mathbf{w} is the best.
- All the points line up best along **u** among all directions orthogonal to *w*. That is

$$\sum_{i=1}^{n} (\mathbf{x}_i^T \mathbf{u})^2 \tag{22}$$

is maximum among all directions orthogonal to w

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is maximum among all directions orthogonal to w

Fact: u is the second eigenvector of $X^T X$ corresponding to the second largest eigenvalue $\lambda_2(X^T X)$.

Given a set of points $\mathcal{D} = \{x_1, x_2, \dots, x_n\}$ in \mathbb{R}^d , find the *k*-th best direction where all the points line up best. **Fact:** The *k*-the best direction is the eigenvector of $X^T X$ corresponding to the k - th largest eigenvalue $\lambda_k(X^T X)$.

Using PCA for Dimensionality Reduction

Given k eigenvectors $\mathbf{e}_1, \mathbf{e}_2, \dots, \mathbf{e}_k$ corresponding to k largest eigenvalues. We can then represent each new data point $\mathbf{x}_i \in \mathcal{D}$ as:

$$\begin{bmatrix} \mathbf{x}_i^T \mathbf{e}_1 \\ \mathbf{x}_i^T \mathbf{e}_2 \\ \vdots \\ \vdots \\ \mathbf{x}_i^T \mathbf{e}_k \end{bmatrix}$$

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Singular Value Decomposition

Let *M* be a $m \times n$ matrix. Let *r* be the rank of *M*. A Singular Value Decomposition is a decomposition of *M* into three matrices U, Σ, V where:

- U is a column-orthogonal $m \times r$ matrix, i.e, $U^T U = \mathbf{I}_m$
- Σ is a diagonal r × r matrix. Elements on the diagonal of Σ are singular values and are *decreasingly* ordered.
- V is an column-orthogonal $n \times r$ matrix, i.e, $V^T V = \mathbf{I}_n$



SVD

$$\begin{bmatrix} 1 & 1 & 1 & 0 & 0 \\ 3 & 3 & 3 & 0 & 0 \\ 4 & 4 & 4 & 0 & 0 \\ 5 & 5 & 5 & 0 & 0 \\ 0 & 0 & 0 & 4 & 4 \\ 0 & 0 & 0 & 5 & 5 \\ 0 & 0 & 0 & 2 & 2 \end{bmatrix} = \begin{bmatrix} .14 & 0 \\ .42 & 0 \\ .56 & 0 \\ .70 & 0 \\ 0 & .60 \\ 0 & .75 \\ 0 & .30 \end{bmatrix} \begin{bmatrix} 12.4 & 0 \\ 0 & 9.5 \end{bmatrix} \begin{bmatrix} .58 & .58 & .58 & 0 & 0 \\ 0 & 0 & 0 & .71 & .71 \end{bmatrix}$$
$$M \qquad \qquad U \qquad \Sigma \qquad V^{\mathrm{T}}$$

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Understanding SVD

Think of U, Σ, V as a representation of *concepts* hidden in M.



Two concepts:

ScienceFiction = {TheMatrixAlien,StarWars}
Romance = {Casablanca,Titanic}

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Dimensionality Reduction by SVD

A rank-k SVD approximation of M is the matrix $U_k \Sigma_k V_k^T$ where:

- U_k contains the first k columns of U.
- Σ_k contains k largest elements of Σ .
- V_k contains the first k columns of V.

Dimensionality Reduction by SVD - An Example

$$\begin{bmatrix} 1 & 1 & 1 & 0 & 0 \\ 3 & 3 & 3 & 0 & 0 \\ 4 & 4 & 4 & 0 & 0 \\ 5 & 5 & 5 & 0 & 0 \\ 0 & 2 & 0 & 4 & 4 \\ 0 & 0 & 0 & 5 & 5 \\ 0 & 1 & 0 & 2 & 2 \end{bmatrix} =$$

M'

$$\begin{bmatrix} .13 & .02 & -.01 \\ .41 & .07 & -.03 \\ .55 & .09 & -.04 \\ .68 & .11 & -.05 \\ .15 & -.59 & .65 \\ .07 & -.73 & -.67 \\ .07 & -.29 & .32 \end{bmatrix} \begin{bmatrix} 12.4 & 0 & 0 \\ 0 & 9.5 & 0 \\ 0 & 0 & 1.3 \end{bmatrix} \begin{bmatrix} .56 & .59 & .56 & .09 & .09 \\ .12 & -.02 & .12 & -.69 & -.69 \\ .40 & -.80 & .40 & .09 & .09 \end{bmatrix}$$
$$U \qquad \Sigma \qquad V^{\mathrm{T}}$$

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Dimensionality Reduction by SVD - An Example A rank-2 approximation of *M*':

$$\begin{bmatrix} .13 & .02\\ .41 & .07\\ .55 & .09\\ .68 & .11\\ .15 & -.59\\ .07 & -.73\\ .07 & -.29 \end{bmatrix} \begin{bmatrix} 12.4 & 0\\ 0 & 9.5 \end{bmatrix} \begin{bmatrix} .56 & .59 & .56 & .09 & .09\\ .12 & -.02 & .12 & -.69 & -.69 \end{bmatrix}$$
$$= \begin{bmatrix} 0.93 & 0.95 & 0.93 & .014 & .014\\ 2.93 & 2.99 & 2.93 & .000 & .000\\ 3.92 & 4.01 & 3.92 & .026 & .026\\ 4.84 & 4.96 & 4.84 & .040 & .040\\ 0.37 & 1.21 & 0.37 & 4.04 & 4.04\\ 0.35 & 0.65 & 0.35 & 4.87 & 4.87\\ 0.16 & 0.57 & 0.16 & 1.98 & 1.98 \end{bmatrix}$$

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Dimensionality Reduction by SVD - Why?

Theorem

Given M, a rank-k SVD approximation of M, denoted by $A_k = U_k \Sigma_k V_k^T$ has:

$$||M - A_k||_F \tag{24}$$

minimum among all possible rank-k matrices.

 $||X||_F$ is the *Frobenius norm* of X:

$$||X||_{F} = \sqrt{\sum_{i=1}^{n} \sum_{j=1}^{m} X[i,j]^{2}}$$
(25)

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Choose k so that at least 90% of energy of Σ is preserved.

$$\operatorname{Energy}(\Sigma) = \sum_{i=1}^{r} \Sigma[i, i]^2$$
(26)

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Querying Concept

	Matrix	Alien	Star Wars	Casablanca	Titanic
Joe	1	1	1	0	0
Jim	3	3	3	0	0
John	4	4	4	0	0
Jack	5	5	5	0	0
Jill	0	0	0	4	4
Jenny	0	0	0	5	5
Jane	0	0	0	2	2

Suppose that a new person P has seen only one movie the Matrix and rated it 4. Recall:

$$\begin{bmatrix} 1 & 1 & 1 & 0 & 0 \\ 3 & 3 & 3 & 0 & 0 \\ 4 & 4 & 4 & 0 & 0 \\ 5 & 5 & 5 & 0 & 0 \\ 0 & 0 & 0 & 4 & 4 \\ 0 & 0 & 0 & 5 & 5 \\ 0 & 0 & 0 & 2 & 2 \end{bmatrix} = \begin{bmatrix} .14 & 0 \\ .42 & 0 \\ .56 & 0 \\ .70 & 0 \\ 0 & .60 \\ 0 & .75 \\ 0 & .30 \end{bmatrix} \begin{bmatrix} 12.4 & 0 \\ 0 & 9.5 \end{bmatrix} \begin{bmatrix} .58 & .58 & .58 & 0 & 0 \\ 0 & 0 & 0 & .71 & .71 \end{bmatrix}$$
$$M \qquad U \qquad \Sigma \qquad V^{\mathrm{T}}$$

Querying Concept (Contt.)

Let \mathbf{q} be the row representation of P, that is:

$$\mathbf{q} = \begin{bmatrix} 4 & 0 & 0 & 0 \end{bmatrix} \tag{27}$$

We can determine the "concept space" of P by:

$$\mathbf{q}V = \begin{bmatrix} 2.32 & 0 \end{bmatrix} \tag{28}$$

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Computing SVD

Recall

$$M = U\Sigma V^{T}$$
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Hence,

$$M^{T}M = V\Sigma U^{T}U\Sigma V^{T} = V\Sigma^{2}V^{T}$$
(30)

which implies:

$$M^{T}MV = V\Sigma^{2}$$
(31)

Conclusion: V is the set of eigenvectors of $M^T M$. By the same argument, U is the set of eigenvectors of MM^T . **Question:** What is Σ ?